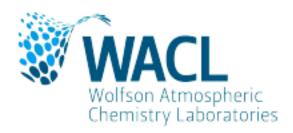
# Oizom O3

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#### **Device Information**

The calibration(s) were completed on:

- 29/07/21
- no second calibration

## **Equations Used**

$$cRMSE(R, L) = \sqrt{mean(L_i - R_i - \overline{L} + \overline{R})^2}$$

- $R_i$  = reference measurement at time i for measurements 1 to n
- $L_i = LCS$  (low cost sensor) measurement at time i for measurements 1 to n
- $\overline{L}$  = mean LCS measurement
- $\overline{R}$  = mean reference measurement

$$RMSE(R, L) = \sqrt{mean(R_i - L_i)^2}$$

- $R_i$  = reference measurement at time i for measurements 1 to n
- $L_i = LCS$  (low cost sensor) measurement at time i for measurements 1 to n
- n = number of measurements

$$Bias(R, L) = |\overline{L} - \overline{R}|$$

- $\overline{L}$  = mean LCS measurement
- $\overline{R}$  = mean reference measurement

## **Comparison Plots**

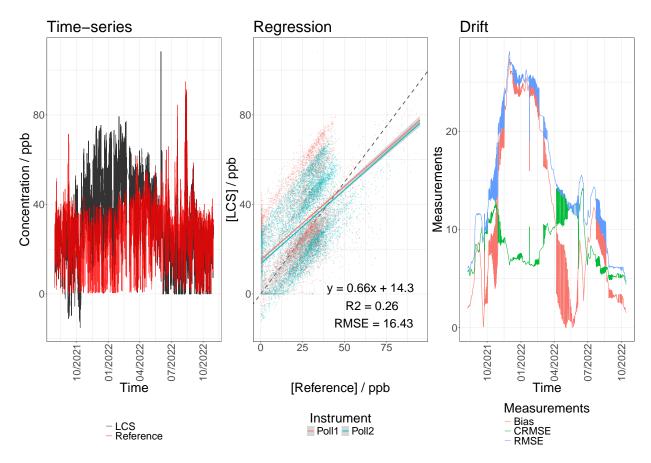


Figure 1: Quantiative evaluation. Column 1: Time-series plot of the LCS measurements (black line) vs the reference measurements (red line). Column 2: Regression plot against reference data. The grey dashed line represents y=x. Column 3: Measure of drift plot (blue line indicates root mean squared error, the red line represents the mean bias and the green line shows the centered root mean squared error).